



School of Physical and  
Occupational Therapy



McGill Faculty of  
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EXCELLENCE THROUGH GROWTH

# Enhancing motor learning using virtual rehabilitation: New ways to deliver old tricks

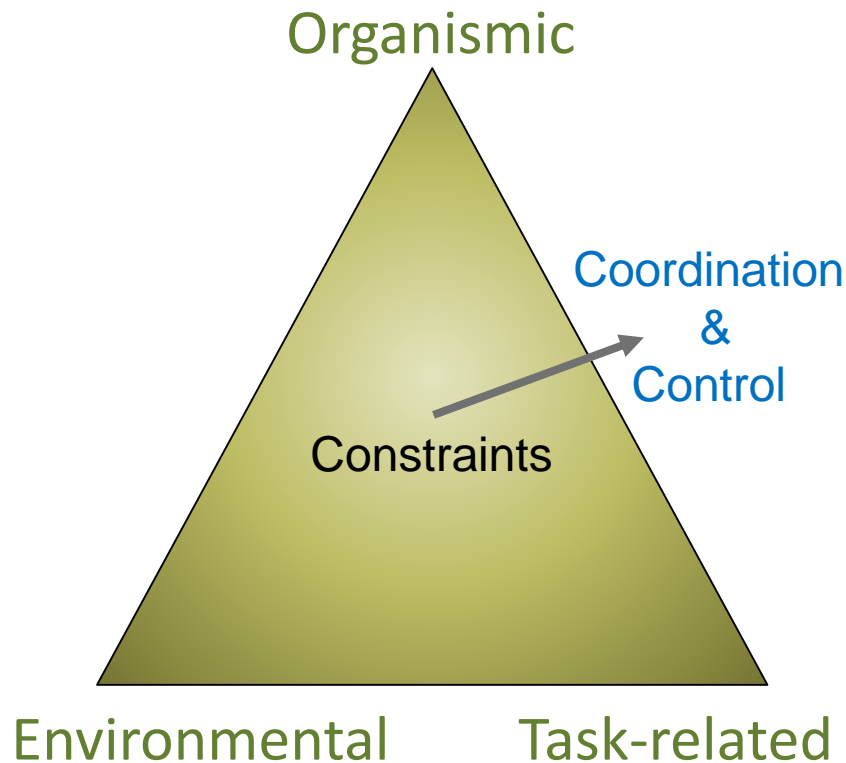
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Canada Research Chair in Motor  
Recovery and Rehabilitation



# Dynamical Approach to Motor Learning

Emphasizes dynamics of change in the movement sequence and its outcome over practice



- Idea that skill learning is reflected in the mastery of redundant degrees of freedom (DFs) – Bernstein (1930's).
- Problem-solving system that uses available constraints and possibilities to discover solutions to a movement problem.
- Acquiring coordination is not hampered by the many interacting variables (i.e., joint DFs) but simplified by them.
- Allows exploitation of the natural properties of the system.
- Emergent rather than reductive approach
- Gives rise to adaptability based on task demands and constraints.

*Thelen, 1995; Newell 1996; van Dijk et al. 2016*

# Ten principles of experience-dependent neural plasticity

Kleim JA and Jones TA. J Speech Lang Hear Res 51:5225, 2008.

1. Use it or Lose It
2. Use it and Improve It
3. Specificity
4. Repetition Matters
5. Intensity Matters
6. Time Matters
7. Salience Matters
8. Age Matters
9. Transference
10. Interference



**Motivation**

**Fun!**

# Motivation



## - crucial for motor learning

Dopaminergic projections from ventral tegmental area (signaling reward) to primary motor cortex mediate motor skill learning (Hosp et al. 2011)

Behavioral research supports motivational effects (including perceived competence) on motor learning (Krakauer 2006, Kleim 2008, Lewthwaite and Wulf 2012)

Reward improves long-term skill retention (Abe et al. Curr Biol. 2011)



# Virtual Reality for Rehabilitation

- ❖ A computer-based technology that provides the user with opportunities to interact with virtual objects and events that appear, sound, and in some cases feel, similar to those of the real world (Wilson et al. 1997).



# Immersion

**Extent to which technology can deliver an illusion of reality.**

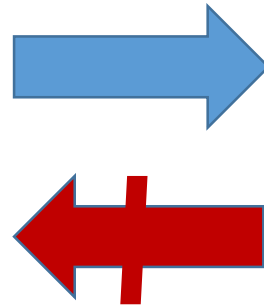
Perception of being physically present in a non-physical world. The perception is created by surrounding the user with images, sounds or other stimuli that provide an engrossing total environment.



# Presence

**State of consciousness of being in a virtual environment.**

Subjective experience of being in one place or environment even when being physically situated in another.



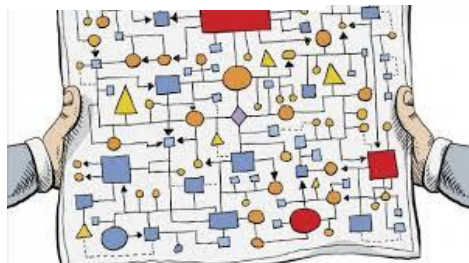
Slater & Wilber, 1997, Witmer & Singer, 1998

# Immersion is multi-modal





# Full Immersion



## Cybersickness



Luque-Moreno et al 2015

- Increased heart rate (Maron et al. 2016)
- + • Altered kinematics in reaching tasks (Powell et al. 2015)
- Reduced postural stability (Treleavan et al. 2015)

## Solution

## Incomplete immersion\*

*\*potential for sensory conflict*

- Fewer side effects
- Better outcomes (Buttussi & Chittaro 2017; La Priore et al. 2003)





# Attributes of virtual rehabilitation



# Caveat

Virtual rehabilitation is not equivalent to video-game applications for cognition, brain fitness and physical fitness

→ Brain Age (Nintendo DS) [www.touchgenerations.com](http://www.touchgenerations.com)

→ Lumosity ([www.lumosity.org](http://www.lumosity.org)) – visual attention & working memory (Scanlon et al. 2007)

→ MindFit – attention, working memory, sensorimotor control (Korczyn et al. 2007)

→ Nintendo Wii

→ Sony Eye Toy

→ Microsoft Kinect



Mindfit Inc.



lumosity  
reclaim your brain™



# Virtual rehabilitation – more than just play

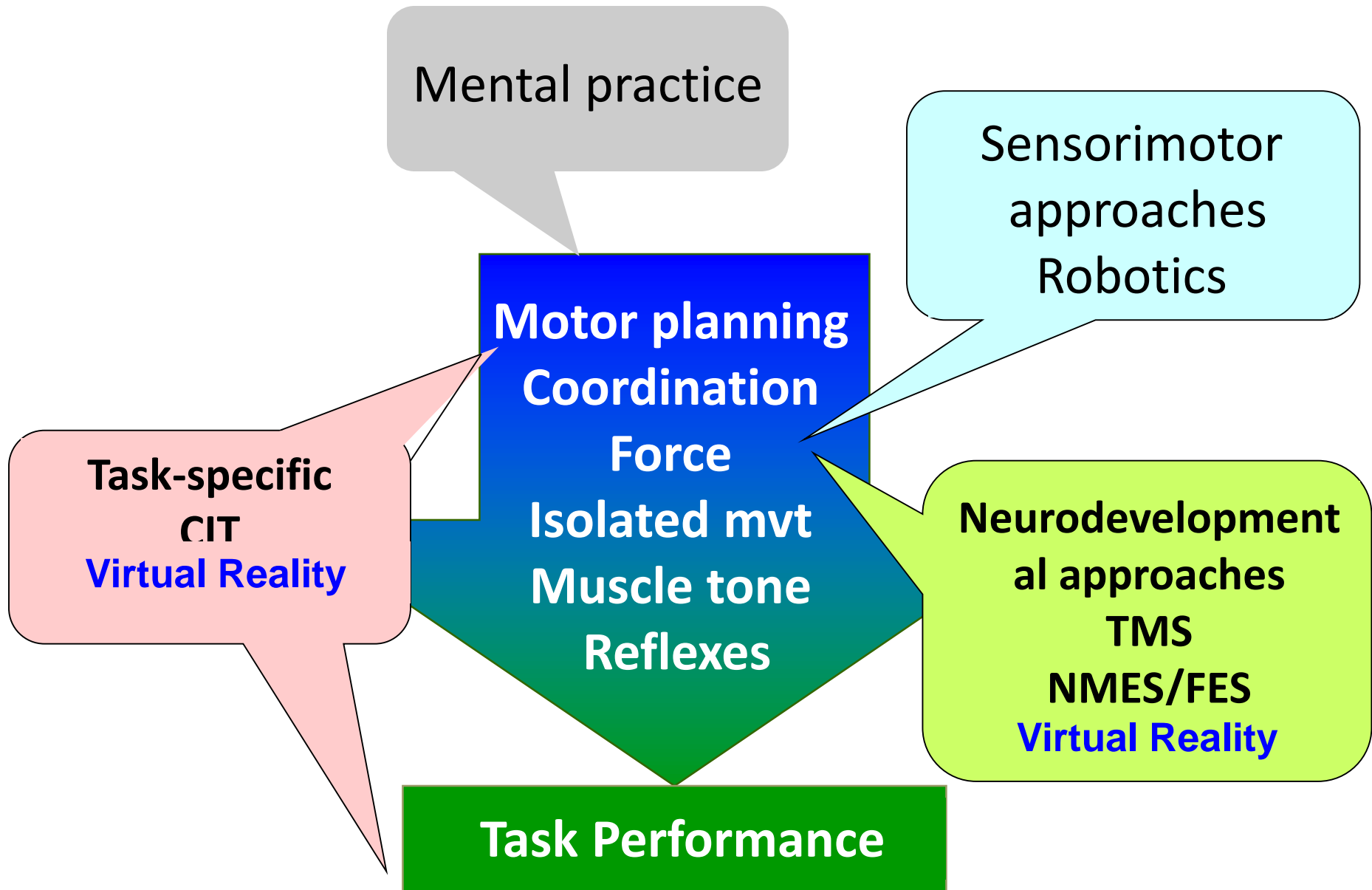
## VR applications

- Rich, controllable multi-modal stimulation
- Intrinsic (task-related) feedback - salient
- Programmable extrinsic feedback
- Learning by problem-solving – cognitive and motor
- Motivation and arousal
- Individualized activities
- Individualized progression of level of difficulty

## Video games

- Rich, multi-modal stimulation
- Intrinsic (movement-related) feedback - unfocused
- Fixed extrinsic feedback
- Not focused on learning, but gains in skills are assumed
- Motivation and arousal
- **X**
- Progression of difficulty according to skill level

# Interventions for sensorimotor rehabilitation



# Types of virtual rehabilitation applications

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- ➔ Teacher-animation
- ➔ Problem-solving scenarios
- ➔ Game-like
- ➔ Immersive, multi-modal, augmented reality

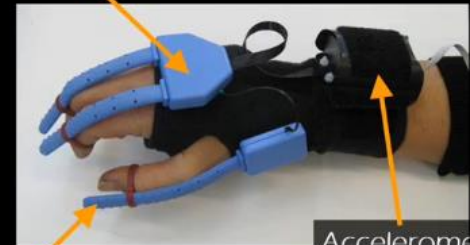


# Teacher-animation



YouGrabber ETH Zürich

Vibration feedback



Modular bend sensors

Accelerometers  
Digital compass  
Camera tracking

## Exercise prescription

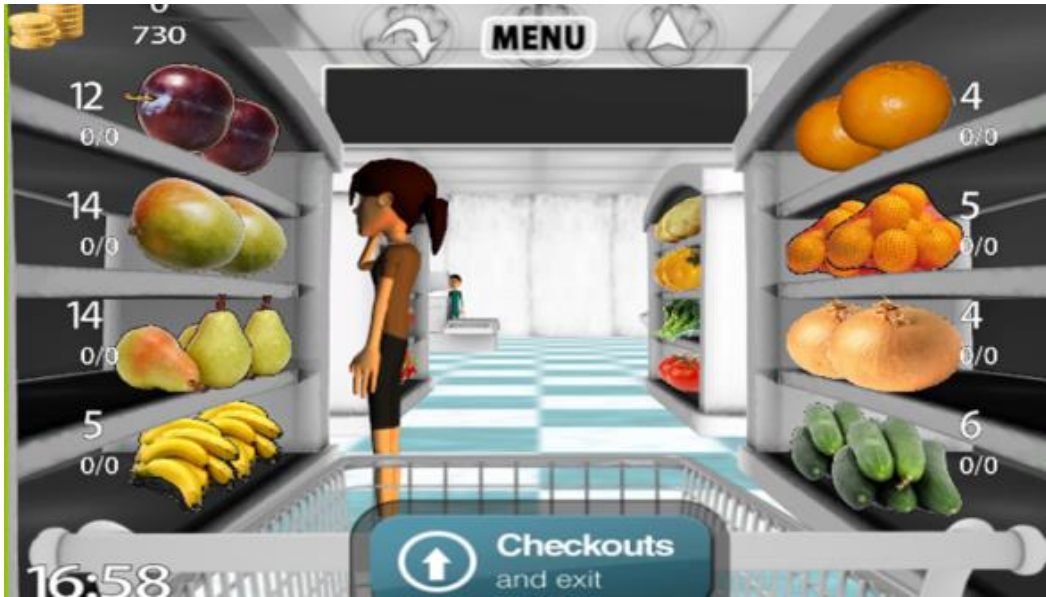
- Home program compliance





# Problem-solving

Scenarios that involve tasks that can be used to identify and provide metrics about users' cognitive and motor abilities





# Game-like

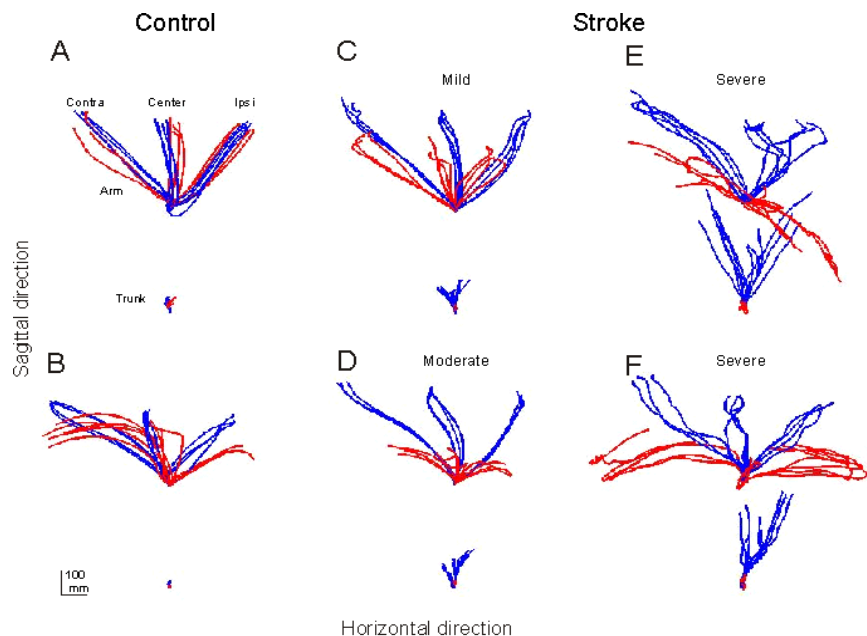


# Video-capture VR environments

**GestureTek**  
HEALTH



## Caveat – movements made in 2D VR



Liebermann et al. TNSRE, 2012



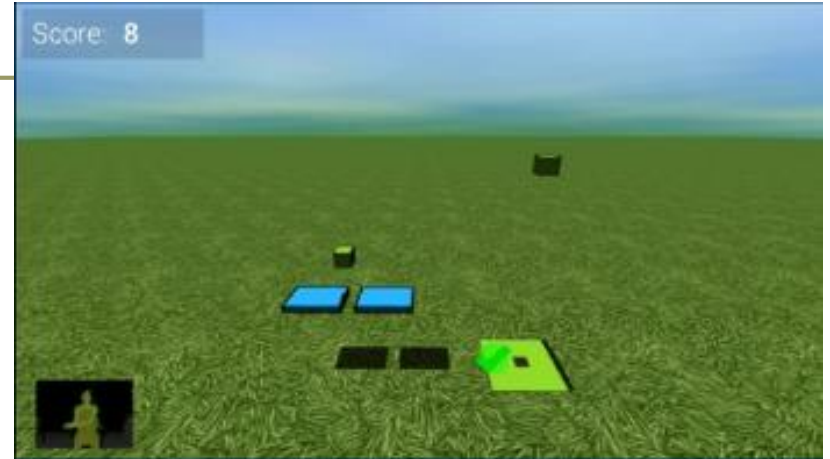
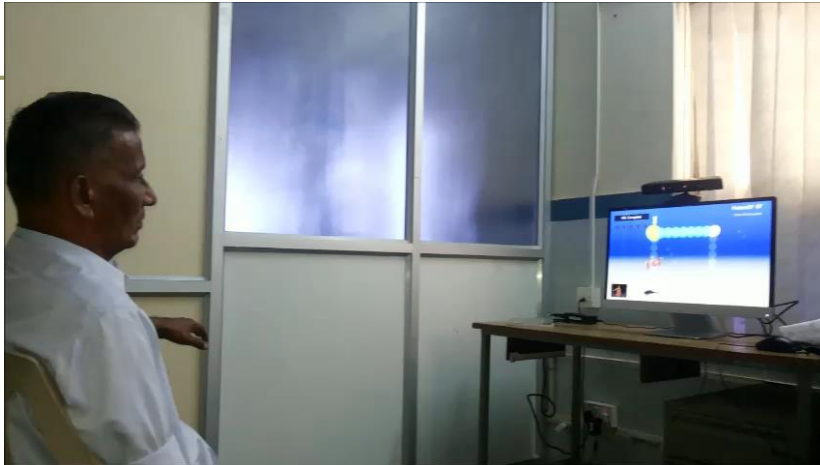
Levin Fagkongres April 2018





# Game-like

## Jintronix Rehabilitation System.



**JINTRONIX**

Montreal, Quebec

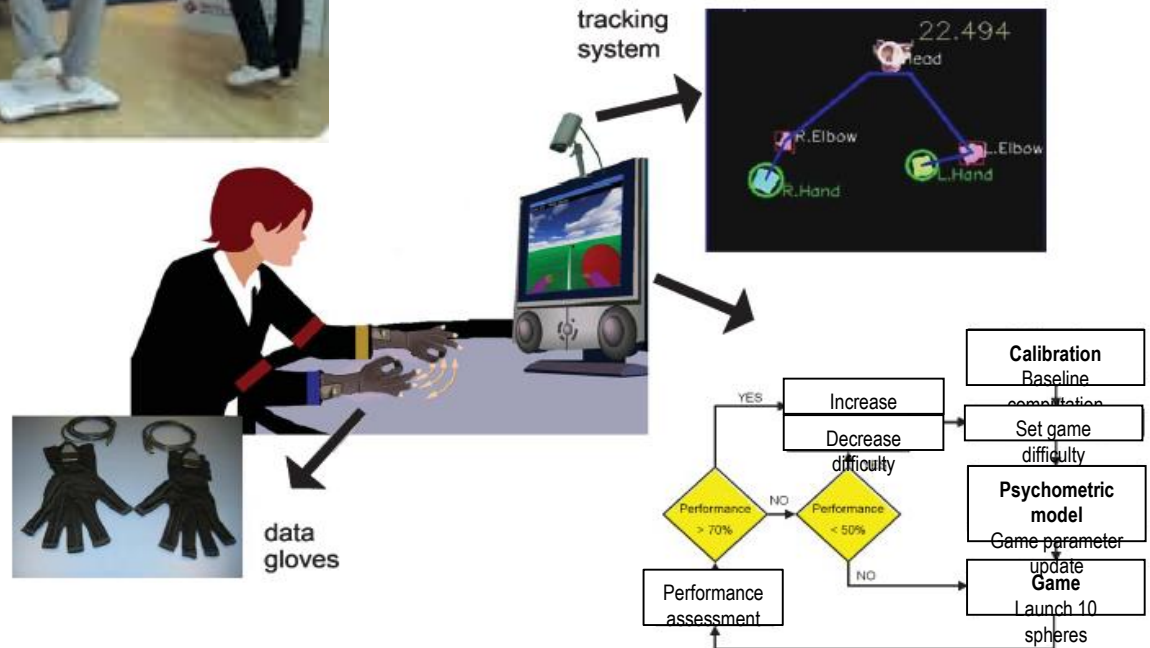


# Game-like

## Fall prevention / balance training



## Reaching training



## Personalized Training Module (PTM)



# Immersive multi-modal

## Dual task performance within a functional VE



Jewish Rehabilitation  
Hospital Montreal

Levin Fagkongres April 2018



# → Immersive

## Pain management



Snow world – Hunter Hoffman





# Immersive

## Anxiety, fear, PTSD

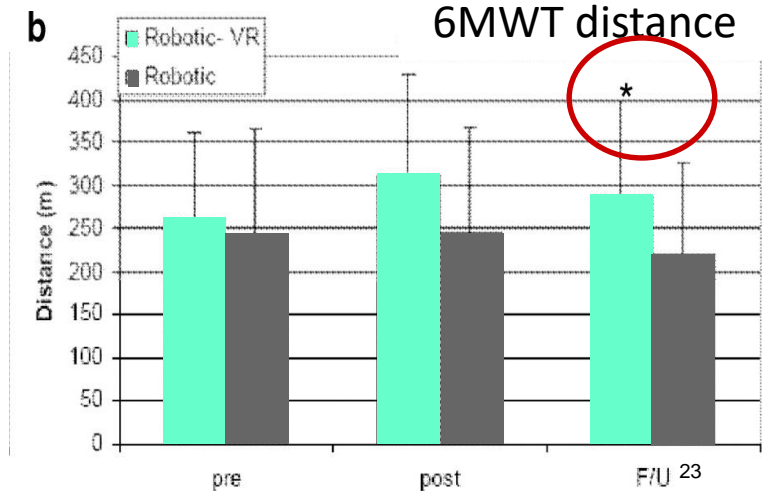
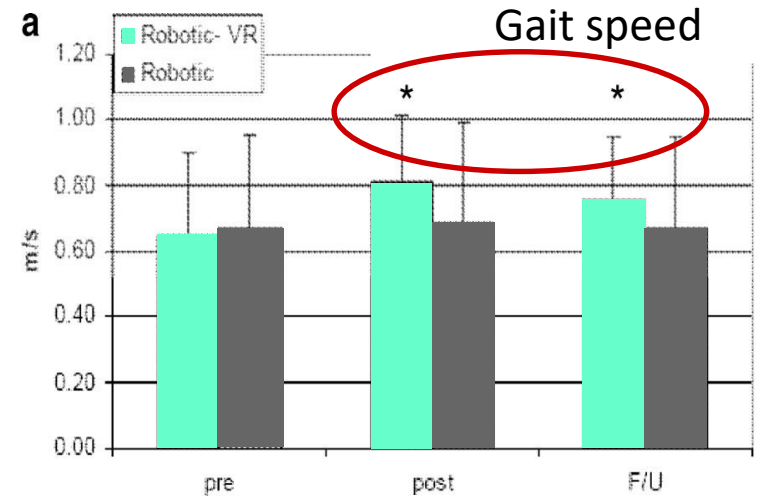
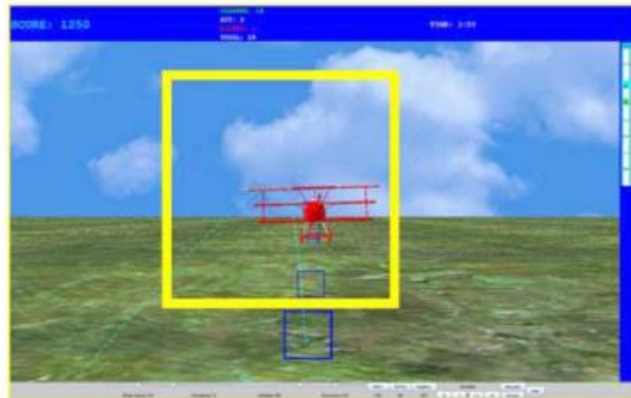
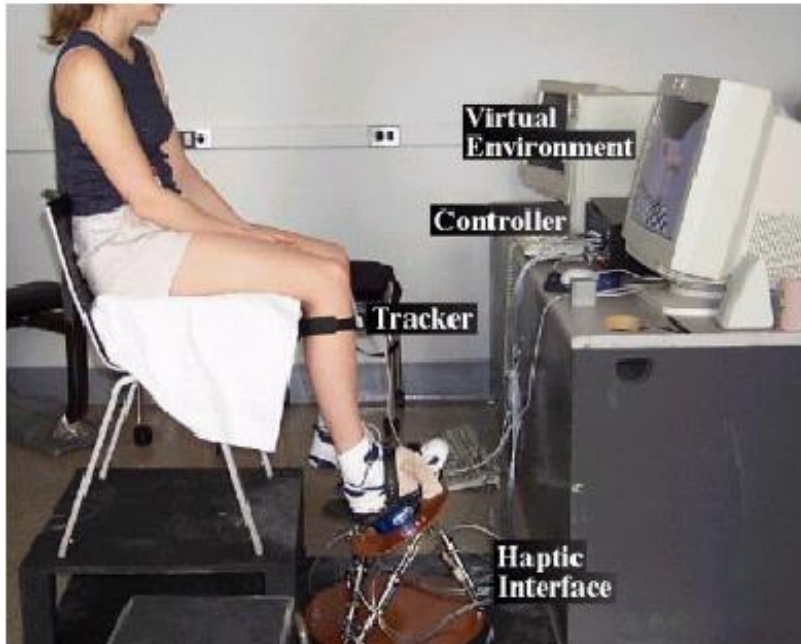


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# Type of Practice

# Task-related practice in VR vs non-specific practice

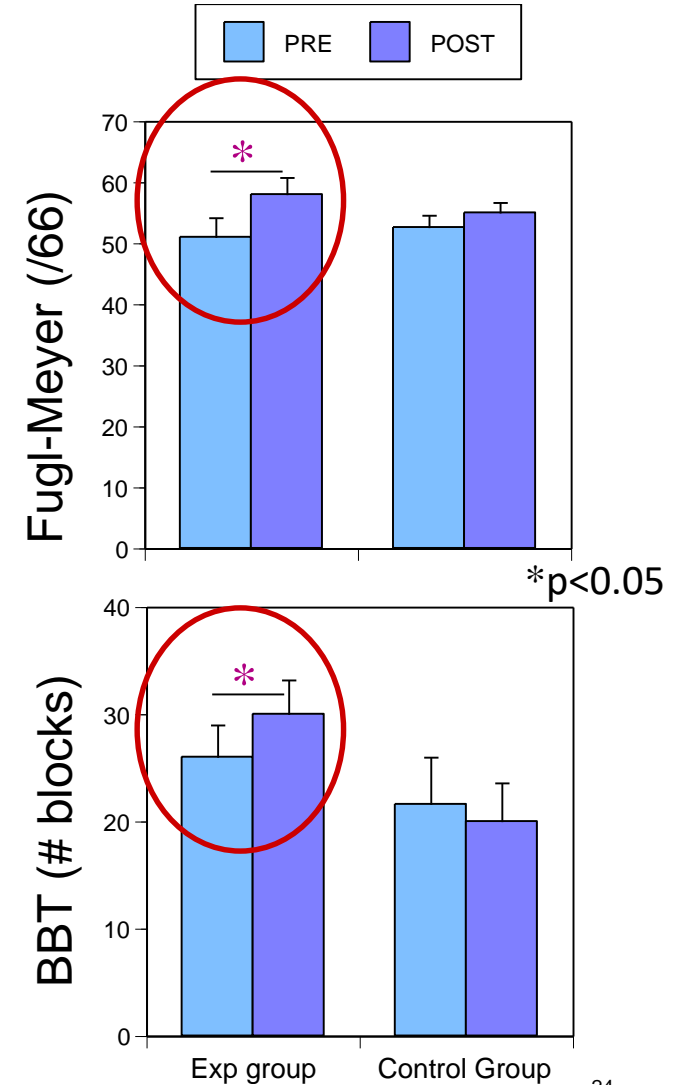
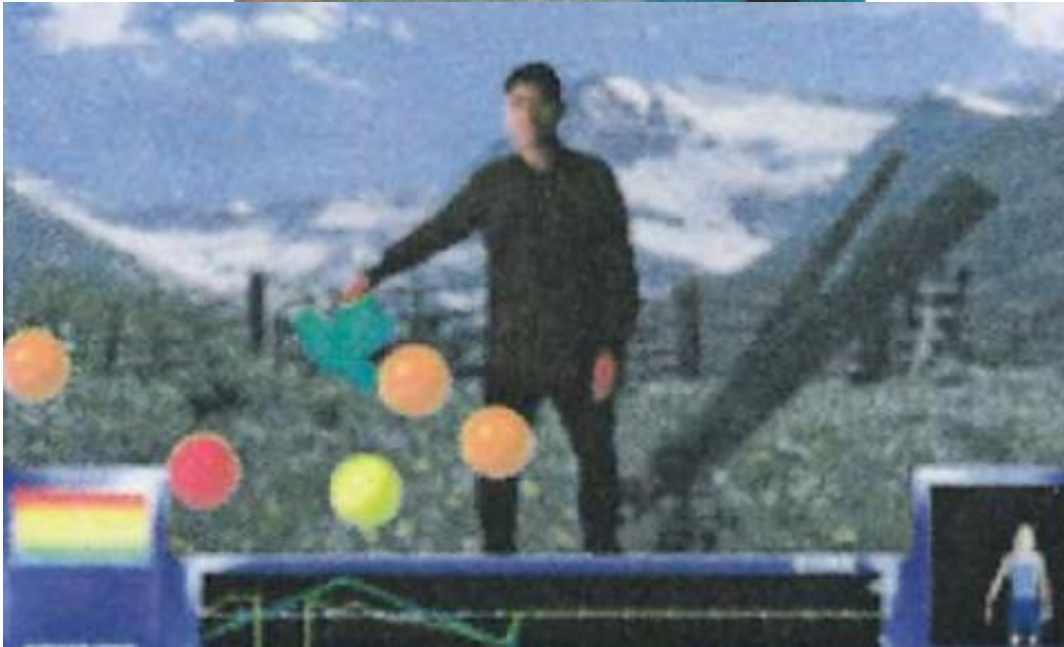
Mirelman et al., *Stroke*; 40(1):169-74, 2009



# Differential (variable) practice

Jang et al., APMR, 86:2218-23, 2005

Chronic stroke (n=5 per group), practice in VR compared to no treatment, 60 mins/day, 5 x/wk, 4 wks





# Feedback: Internal vs external focus of attention

**Internal focus:** attention is directed at the movements composing the motor action



**External focus:** attention is directed at the effect of the movement: goal



# Feedback – Knowledge of Results (KR)

- **Positive feedback** - movement is both temporally and spatially successful (high pitched 'ping' sound, target turns green)
- **Negative feedback** - movement is not rapid and/or precise enough (buzzer sound, color of the target does not change)



# Feedback – Knowledge of Performance (KP)

- **Excessive trunk motion** – 3<sup>rd</sup> sound emitted ('whoosh'), target turns red (even if the subject's movement was accurate and precise enough)
- Default value for permissible trunk displacement **tolerance** adjustable (i.e. 5 cm)

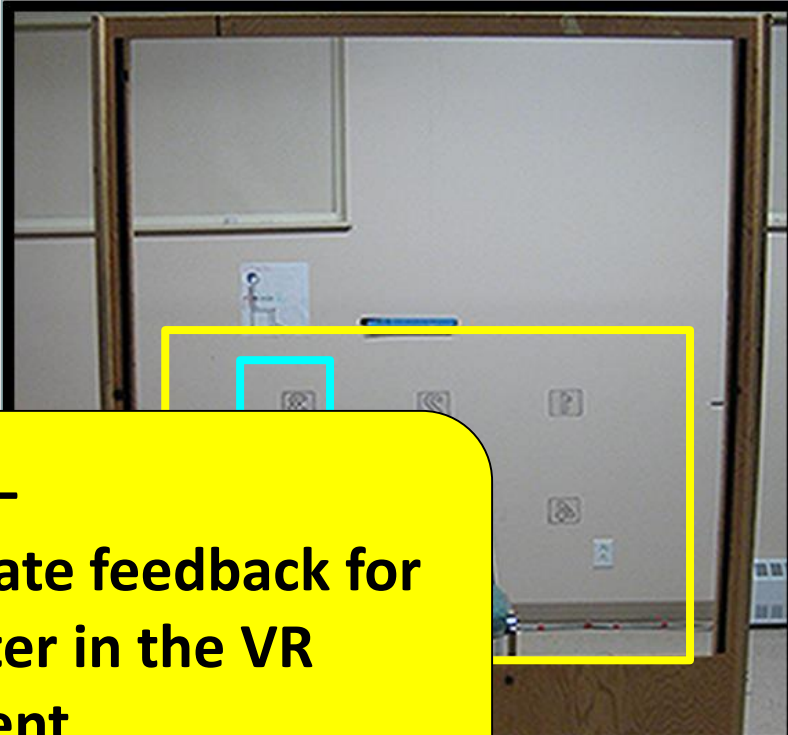


## Training Environment Features

- Same task dimensions and visual array
- Same feedback conditions:
  - terminal KR – movement precision & speed (auditory & visual) – success (ping); failure (buzzer)
  - concurrent negative KP – trunk movement (auditory)
- terminal KR – change in target appearance when successful; contextual

-32 participants with varying levels of severity and random assignment to VR

**Results – patients could incorporate feedback for motor learning better in the VR environment**



Subramanian et al., NNR, 2013

# Feedback delivery schedule



**Continuous** (after every trial)

**Summary** (after a fixed number of trials, general information about all trials)

**Average** (average information about a fixed number of trials)

**Faded** (initially after every trial, then after several trials)

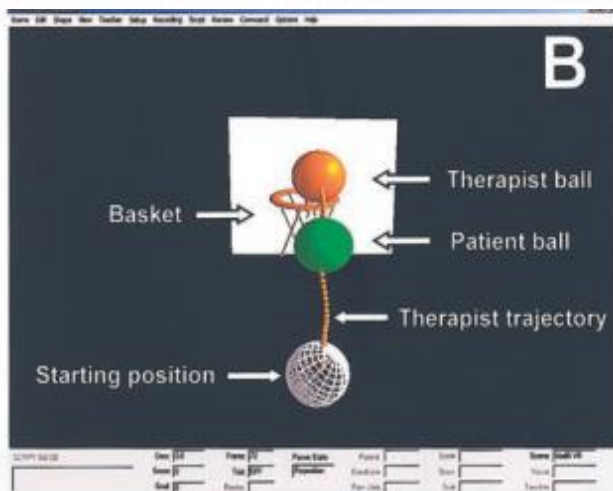
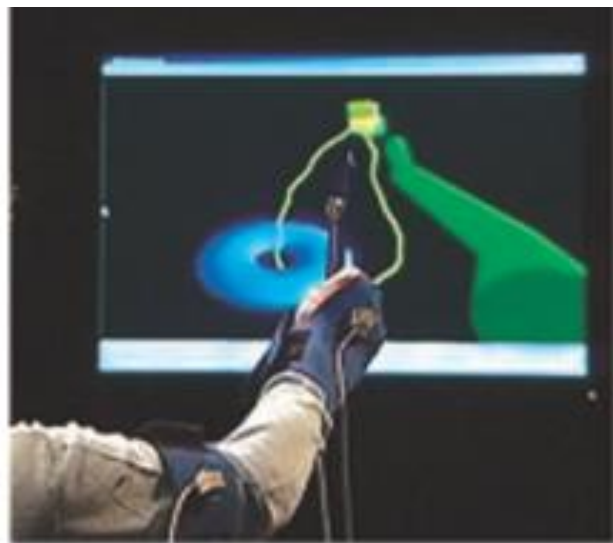
Faded feedback



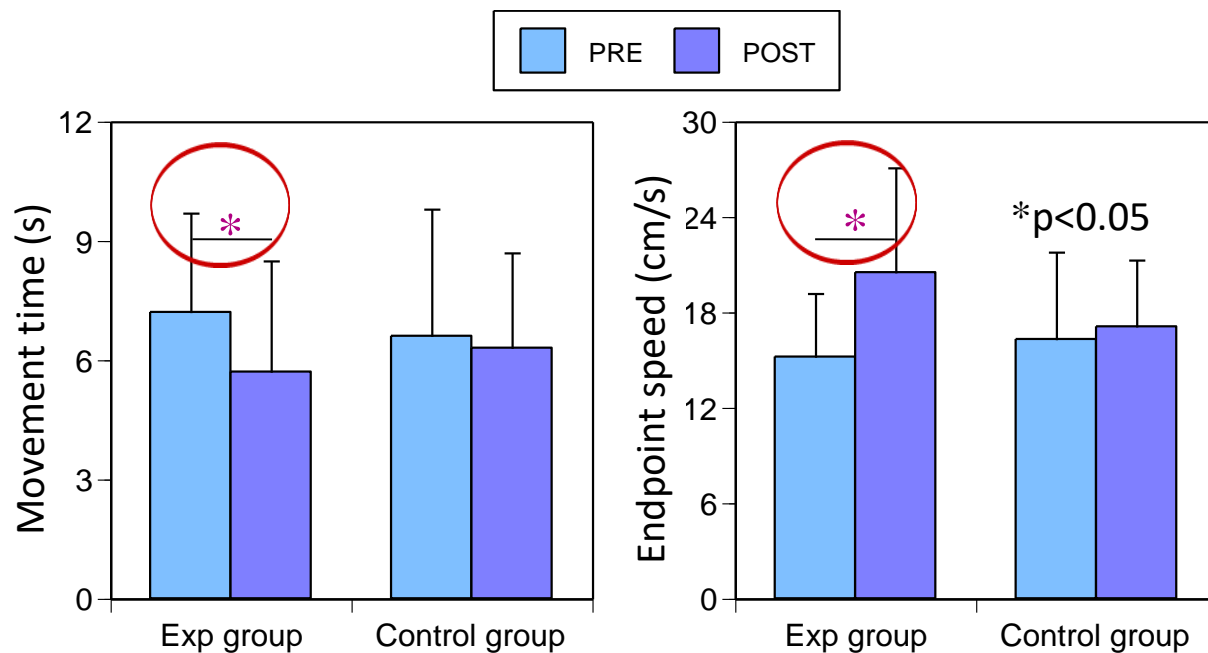
- More opportunity to find own motor solution
- Better retention of learned skills

*(Hebert et al., 1998, Cirstea et al., 2006)*

# Continuous feedback



**Control: Conventional progressive therapy, n=20**  
**Feedback: VR group, n=27** Verbal KP (arm movement) and visual KR (arm vs. teacher trajectory)  
 Chronic stroke; 60 mins/day; 5 days/wk; 4 wks



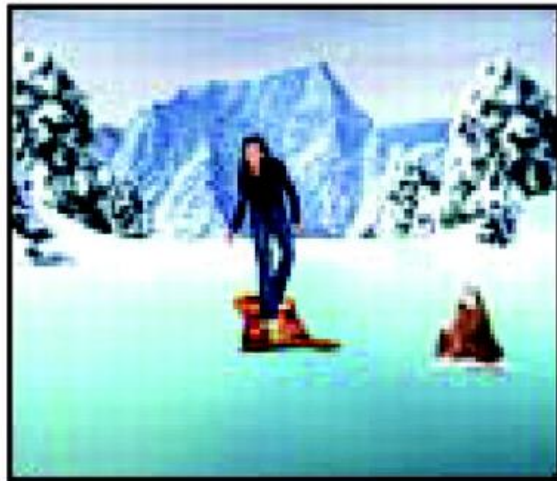
FMA: VE 5.1pts; PE 4.3pts

# Faded feedback

Step Measurement



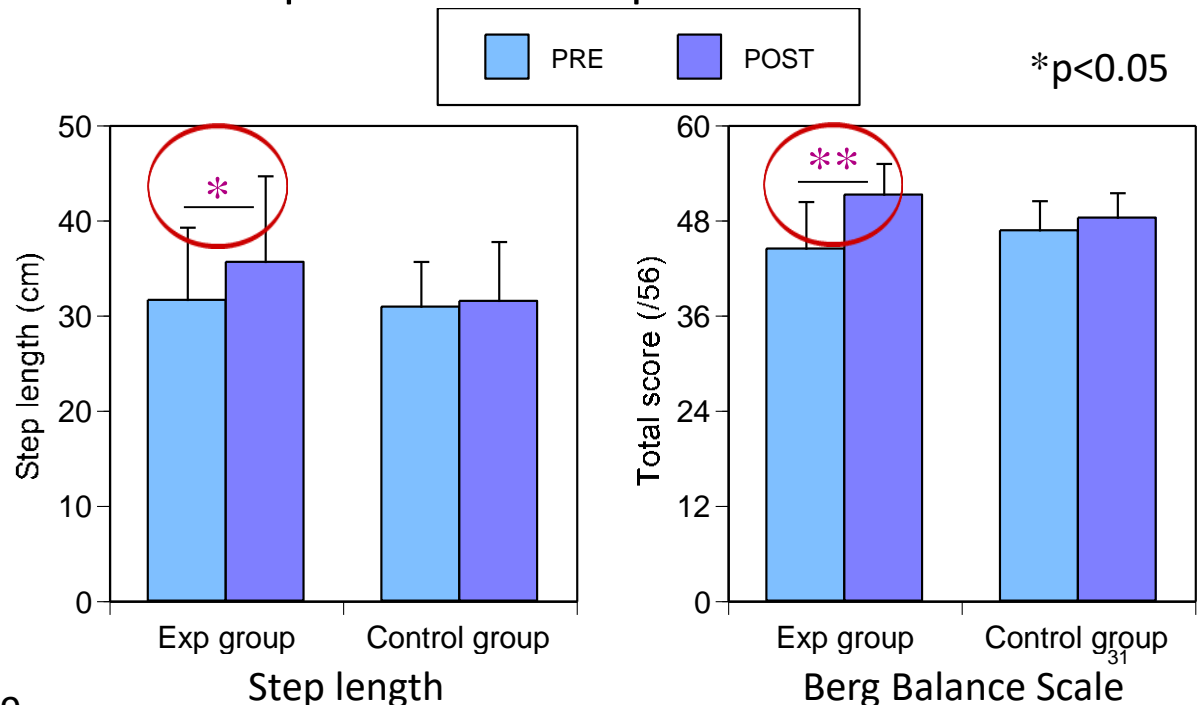
Phase 1: Stand beside the step



**Conventional Tx Group** (n=12) 40 min/day, 4 days/wk, 4 wks.

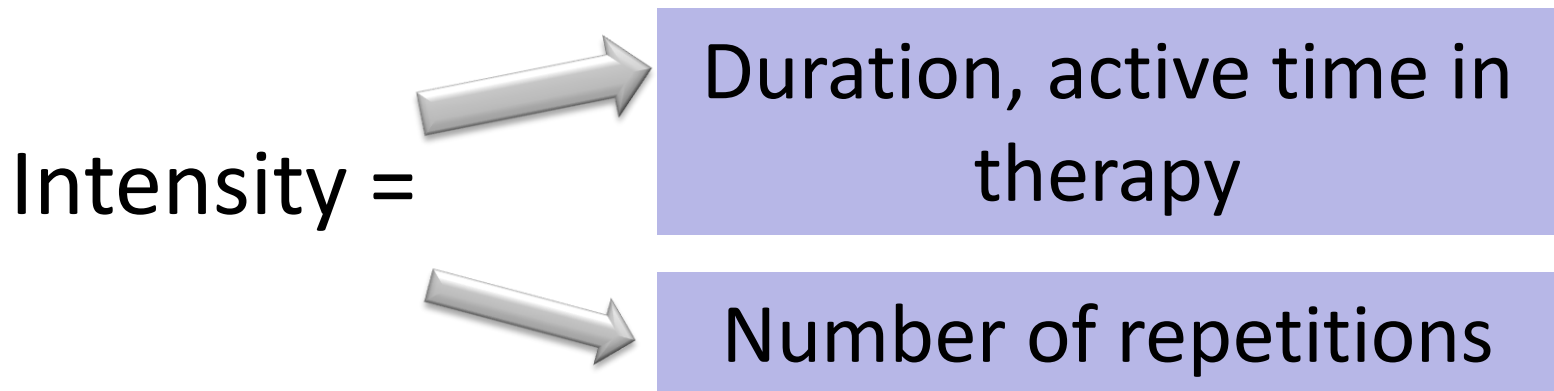
**Experimental Group** (n=12) Conventional Tx + 30 min VR/session

**Feedback:** KR (game score) and KP (body movements). Initially provided > 90% of the time and reduced as performance improved.



# Practice Intensity

□ High intensity practice  $\Rightarrow$  better outcomes.

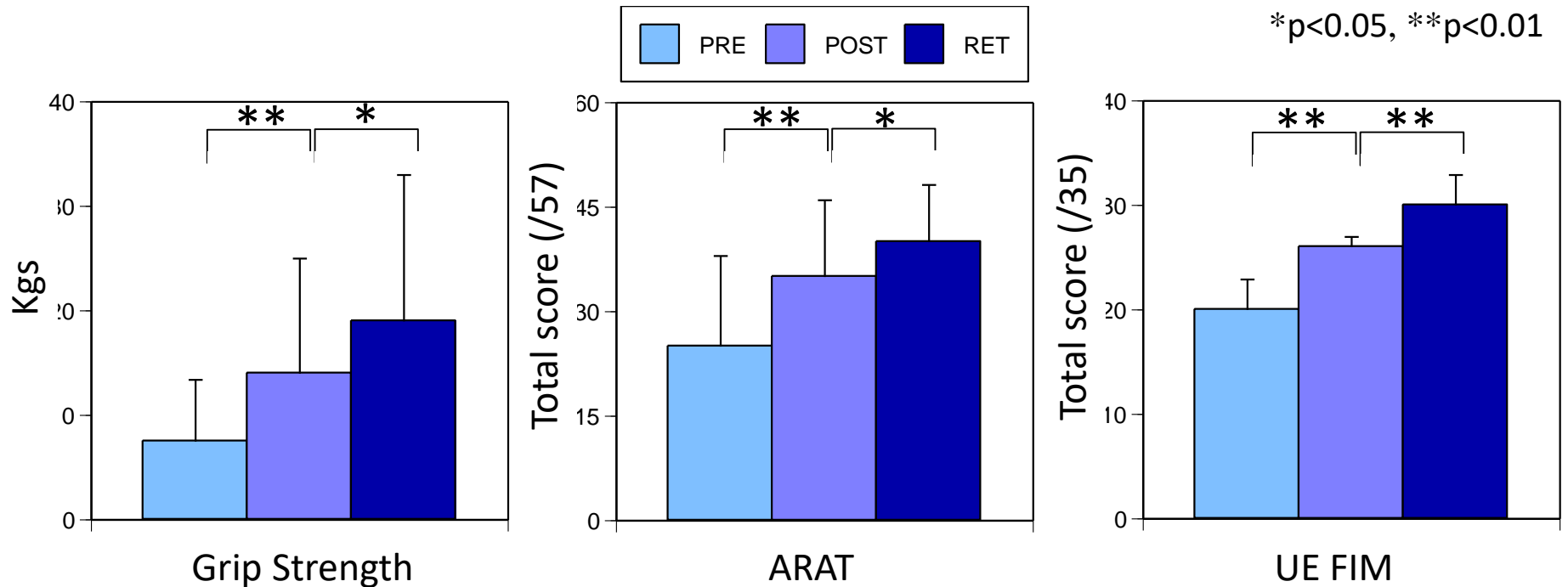


*Lohse et al., 2014*



# Practice Intensity

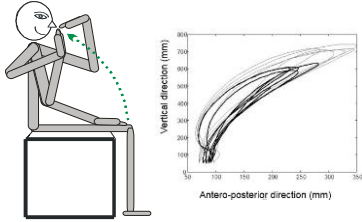
Waddell et al., AJOT, 68(4):444-53, 2014



- High intensity practice (single cohort study, 60 mins per day, 289 ± 35 repetitions) per session for 12 sessions, inpatient hospital setting (n=15; 1 month retention test)

# Motor learning principles that can be addressed in VR

## Redundancy



Task practice with attention to motor compensations  
Multiple repetitions of different movements.  
**Feedback** - explicit to implicit learning focus  
Continuous to faded – search for task solution



## Affordances & Environment



Tasks should be varied in their level of problem-solving to challenge different cognitive and meta-cognitive abilities.  
Task practice – task-oriented  
**Feedback** - focus of attention – external (feedback on task goal)



## Task Difficulty

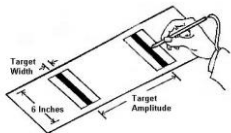
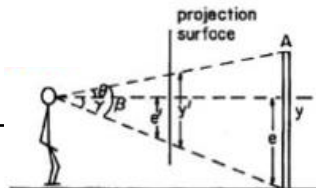


Figure 1. The serial tapping task used by Fitts (1954).

Intensity of practice – high  
Progression of task difficulty according to Fitts' Law  
**Feedback:** precision & speed  
-explicitly mapped to patient performance and progression through difficulty levels.



## Perception



Perceivable properties of environment contain information about actions  
Visual techniques can enhance virtual presence  
**Feedback** – haptic, on object contact to reinforce perception

# Current learning in virtual reality

➔ More research is needed on effectiveness of manipulating type, frequency and delivery schedule of feedback on motor learning

- Possibility to exploit **learning by observation** of avatars of moving limbs (mirror neuron system; *Rizzolatti and Craighero 2004*). Translation between perception of action and action execution – drives **functional reorganization**
- Ability to manipulate **extrinsic feedback** (*Verschure et al. 2003*)
- Opportunity to explore the environment by varied practice – **learning by problem-solving and taking advantage of the system's redundancy** (*Bernstein 1967*)
- Use of environments that increase **motivation and arousal** (*Green and Bavelier 2008*)

## Acknowledgments

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- Anatol Feldman



<http://www.isvr.org>



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**12th International Conference on  
Disability, Virtual Reality & Associated Technologies**

In collaboration with *Interactive Technologies and Games*

**University of Nottingham, England - September 4-6, 2018**

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**SHORT PAPER SUBMISSION DEADLINE: MAY 31, 2018**

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